Environmental Subsidy and Audit Policies with Self-Reporting

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ABSTRACT

Both the subsidy on the investment in abatement of pollution and the tax imposed on the pollution level, subject to possible audit, can be considered two important incentives contributing toward alleviating the costly externalities to pollution generated by optimizing economic firms. Also, under existing environmental regulations, firms are often required to self-report their compliance status to reduce necessary supervising and legal enforcement costs. Assuming the related tax rates of pollution are exogenous, this paper examines the interplay between environmental subsidy and audit policies, specifically under a self-reporting regime, to shed light on some policy implications. One of the major results indicates that, as environmental audit is difficult and costly, the subsidy on the investment in abatement of pollution will be relatively more effective and justifiable. Nevertheless, under a self-reporting regime, there is not such an obvious policy substitutability between subsidy and audit measures as that in Guo and Wang (2004), which has no self-reporting regime.

Key words: subsidy policy; audit policy; self-reporting.

1. INTRODUCTION

In practice, firms are often required to self-report their environmental compliance status to reduce necessary supervising and legal enforcement costs. As Kaplow and Shavell (1994) argue, enforcement schemes with self-reporting offer society two advantages, including saving enforcement resources as well as eliminating risk-bearing costs (a benefit when actors are risk-adverse). Innes (1999) also notes that remediation or clean-up benefits impart two advantages to the employment of self-reporting beyond those identified elsewhere, i.e. self-reporting firms always engage in efficient remediation and the government enforcement effort required to achieve a given level of violation deterrence. Hence, if the self-reporting cost is insignificant, it seems desirable for the regulator to take a self-reporting regime into account as it determines adequate environmental policies.

To induce polluting firms to make necessary investments in environmental protection, investment subsidies can be used as a prominent policy measure to alleviate political economy costs resulting from environmental tax (Arguedas & van Soest 2009). In the prior literature, while Kneese and Bower (1968), Mills (1972), Harberger (1980), Slitor (1976), Baumol and Oates (1979), and Fisher (1983) present some negative opinions on investment tax credit or subsidy from government, there are still a couple of positive viewpoints for subsidy policy. For instance, Laplante (1990) finds, in the Cournot oligopoly market model, if



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government offers some kind of subsidy (e.g. investment tax credit) on de-pollution equipment, it will avoid the collusion between a firm and its competitor, and the firm will undertake the investment in de-pollution equipment and make its output fulfill the optimal demands of society. Kort, van Loon, and Luptacik (1991) point out, while an increase in subsidy rate on investment in de-pollution equipment raises governmental expenditures, more investment in that equipment will foster lower pollution levels and higher economic growth. Thus, it will contribute to future tax revenues and employment opportunities. In particular, subsidy policy has a much more prominent effect on the investment in considerably expensive capital goods. Rajah and Smith (1993) also argue that even if the subsidy on investment in pollution abatement may augment the public sector's expenditures and become a hidden protection, it remains one of the important policy measures that could be coupled with environmental taxes. However, as Isik (2004) notes, the uncertainty on subsidy policies could have some potential impact on the investment decision.

In recent literature, Arguedas and van Soest (2009) show that policies consisting of a menu of emission taxes and investment subsidies can potentially induce firms to self-select as well as aid governments to distinguish between firms that need to receive a subsidy to adopt a new technology and firms that would adopt that technology even without subsidies. Using agent-based simulations, Cantono and Silverberg (2009) explore when a limited subsidy policy can trigger diffusion that would otherwise not happen, and they find that the introduction of a subsidy policy seems to be highly effective for a given high initial price level only for learning economies in a certain range. Toshimitsu (2010) argues that, paradoxically, a subsidy policy degrades the environment, and that an optimal policy depends on the degree of marginal social valuation of environmental damage. That is, if the marginal social valuation of environmental damage is larger than a certain value, a consumer-based environmental subsidy policy is not socially optimal. Furthermore, McGilligan, Sunikka-Blank and Natarajan (2010) examine the impact that subsidy can make in bolstering the performance of an Energy Performance Certificate by reducing carbon emissions in the residential sector. They perform a cost-benefit analysis using the concept of the Shadow Price of Carbon and present a model which allows the carbon savings for any level of subsidy to be calculated. Their model suggests that subsidization of the installation of hot water tank insulation, draught proofing measures, loft insulation and cavity wall insulation may be cost-effective, but that the subsidization of others, most notably interior solid wall insulation, are unlikely to significantly bolster carbon savings.

Provided that a firm has made the necessary investment in abatement of pollution, under a self-reporting regime, there remains some incentive for it not to honestly declare the realized pollution state and pay the required pollution tax. Hence, the audit of pollution state is regarded as an important measure to induce a polluting firm to present an honest report. In the past literature, there has been a lot of research on audit systems, such as Antle (1982 & 1984), Baron and Besanko (1984), Demski and Sappington (1987), Penno (1990), Baiman, Evans and Nagarajan (1991), Kofman and Lawarree (1993 & 1996), etc. Meanwhile, there are also considerable discussions specifically related to environmental audit measure, including Doyle (1992), Morelli (1994), Campbell and Byington (1995), Franckx





(2002), as well as Friesen (2006).

Despite lots of papers concerned with either subsidy or audit policies, little attention has been concentrated on simultaneously dealing with subsidy, audit, and self-reporting in environmental policies. Following the model of Guo and Wang (2004), this paper examines the interplays among these regulatory measures in order to shed light on some policy implications and finds that, under a self-reporting regime, there seems no obvious policy substitutability between subsidy and audit measures. This is a little different from the result of Guo and Wang, which has no self-reporting regime. In next section, we characterize the basic model used in this article. The related analyses and results are presented in section III. Finally, section IV summarizes the prominent results of this research as well as possible policy implications.

2. THE MODEL

It is assumed in this paper that the regulator can manipulate two policy measures, i.e. subsidy and audit, to induce a polluting firm to make a higher investment in abatement of pollution. Meanwhile, the firm's self-reporting regime will be employed under the assumption of no reporting cost. The overall decision process can be regarded as a one-period game played by a firm and a regulator, both of whom are assumed to be risk neutral. Moreover, it is assumed the firm is required to make at least a low investment (I_i) in abatement of pollution without subsidy from the regulator since the related business is a pollution-producing one.

At the beginning of the period concerned, the regulator decides and announces a subsidy rate β (and $\beta \in [0,1]$) for the portion of increased investment $(\Delta I \equiv I_h - I_l)$ if the firm makes a high investment (I_h) rather than a low investment (I_l) in abatement of pollution; i.e., the amount of subsidy is $\beta\Delta I$. The firm will then choose to make either a high or a low investment in abatement of pollution according to the regulator's subsidy policy and subsequent possible audit policy. Furthermore, it is assumed that the firm is required to declare its investment level to the regulator in order to either conform to the lowest investment regulation or apply for an investment subsidy. Thus, the investment level is common information. Similar to the setting of Malik (1993), the pollution generated by the regulated firm is denoted by a binary random variable P and it is the firm's private information. Under low investment, with probability θ , a high pollution state (H) occurs and P takes on high value of P_h ; and with probability $1-\theta$, a low pollution state (L) occurs and P takes on low value of P_l , where $P_l < P_h$. That is, under low investment, Pr (P= P_h = θ and Pr ($P = P_l$) = 1- θ . In this paper, we assume the firm's investment level (or control effort) has an influence on the pollution level of P, rather than on probability of θ^{1} Hence, under high investment, with the same probability of θ , state H will result in a pollution level dP_h , and with probability $1-\theta$, state L will



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¹ θ can be regarded as the probability of a good economy or high output, and 1– θ corresponds to a bad economy or low output.

contribute to a pollution level dP_l , where 0 < d < 1. In other words, it is assumed that Pr $(P = dP_h) = \theta$ and Pr $(P = dP_l) = 1 - \theta$ under high investment. Whatever pollution level happens, it is assumed that social damage cost (external cost) per unit of pollution level is *s*. Furthermore, P_h , P_l , and *d* are all common information.

Under a self-reporting regime, the polluting firm is required to declare the realized state of pollution. Having made a high (low) investment in the abatement of pollution, the firm can choose reporting a pollution level, dP_h or dP_l (P_h or P_l), to the regulator, and then pay a certain amount of pollution tax. In this paper, Y_h and Y_l are the firm's decision variables used for reporting decisions, where $0 \le Y_h \le 1$ and $0 \leq \gamma_l \leq 1$. Meanwhile, $\gamma_h = 1$ ($\gamma_l = 1$) means the firm makes a high (low) investment and honestly declares a high pollution state given state H occurs, but Y_h = 0 ($\gamma_{l} = 0$) implies declaring a low pollution state. Obviously, there is no incentive for a firm to declare a high pollution state if the pollution state is low. Under high (low) investment, the pollution tax will be $tdP_h(tP_h)$ if state H is realized and the firm honestly reports it to the regulator (i.e. $Y_h = 1$ ($Y_l = 1$)), and the pollution tax will be $tdP_l(tP_l)$ if state L is realized and the firm declares a state of low pollution. However, provided the firm presents a report of low pollution after state H occurs (i.e. $Y_h = 0$ or $Y_l = 0$) and is found to be under-declaring by the auditor, the pollution tax will be adjusted up to $t'dP_h$ or $t'P_h$ depending upon whether the firm has made a high or low investment in abatement of pollution. The punitive tax rate, t', is assumed to be larger than the normal tax rate, t, and t is assumed to be less than s. Meanwhile, in consideration of the complexity of the factors influencing tax rates, this paper doesn't intend to deal directly with the issue on optimal pollution tax policy. Both t and t' are assumed to be exogenously determined. Nevertheless, via the use of audit policy, the regulator still can determine an optimal value of "expected pollution tax revenues" given the pollution tax rates. Sandmo (2002) and Backlund (2003) have some discussions on the related issues.

Since there is an economic incentive for the firm to under-declare the pollution state (when state H occurs) and to avoid higher pollution tax, the regulator can consider taking an audit action to verify the firm's report (when the latter declares a low pollution state). In the model, the regulator will choose an audit probability (α_h or α_l) depending upon the investment level (I_h or I_l) to verify the firm's report of a low pollution state. In the latter analyses, A denotes the cost of a complete audit, and q represents the audit quality, which is the probability that the audit result correctly shows the state is H given state H occurs. In contrast, 1-q is the probability that the audit result shows the state is L given the realized pollution state is L. For simplification, it is assumed the probability that the audit result shows the state is L given state L occurs is one.

The timing of the related events in the model is summarized as follows:

- (1) At the beginning of the period concerned, the regulator announces a subsidy policy of investment in abatement of pollution. The subsidy rate for the portion of increased investment $(\Delta I \equiv I_h I_l)$ is β , where $\beta \in [0, 1]$.
- (2) The firm will then choose to make a high or low investment $(I_h \text{ or } I_l)$ in abatement of pollution in consideration of the regulator's subsidy policy and subsequent audit policy.





- (3) Nature determines whether the state of pollution is "high" (with probability of θ) or "low" (with probability of 1θ).
- (4) Depending on the actual investment level and the realized state of nature, the firm decides to declare a high (*H*) or low (*L*) pollution state to the regulator in consideration of the regulator's audit policy and will pay the pollution tax calculated by a normal tax rate, *t*, if the report is not found incorrect.
- (5) According to the actual investment level $(I_h \text{ or } I_l)$, which is common information, the regulator will decide an audit probability $(\alpha_h \text{ or } \alpha_l)$ of sending an independent auditor (at a cost of *A*) to verify the firm's report of low pollution state.
- (6) Given a realized state of high pollution and a report of low pollution state presented by the firm, there is a probability of q that the audit action will reveal a high pollution state if audit action has been undertaken. When the firm is found to be under-declaring the pollution state, the pollution tax will be calculated by a higher (punitive) tax rate, t', instead of t.
- (7) Transfers are realized.
- A representation of the game model is shown in Figure 1, with the definitions of related variables being shown in Table 1.



Figure 1. Game tree^{*}.





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^{*}R: regulator.

F: firm.

N: nature.

b: subsidy. *a*: audit.

na: no audit.

H: nature determines a high pollution state.

L : nature determines a low pollution state.

H': the firm declares a high pollution state.

L': the firm declares a low pollution state. $E(C^R)_i$: net expected external costs (considered by regulator) in track i. $E(C^F)_i$: net expected environment costs (related to firm) in track i, and the others follow the same definitions as aforementioned.

Table 1. Definitions of variables

Variable	Definition		
I_l	The amount of low investment in abatement of pollution.		
I_h	The amount of high investment in abatement of pollution.		
ΔI	The portion of increased investment ($\equiv I_h - I_l$).		
β	Subsidy rate announced by the regulator ($\in (0,1)$).		
Н	High pollution state.		
L	Low pollution state.		
H'	High pollution state reported by the firm.		
L'	Low pollution state reported by the firm.		
P_h	Pollution level under low investment and state H.		
P_l	Pollution level under low investment and state L.		
dP_h	Pollution level under high investment and state <i>H</i> , where $0 < d < 1$.		
dP_l	Pollution level under high investment and state <i>L</i> , where $0 < d < 1$.		
θ	The probability that high pollution state occurs.		
$1-\theta$	The probability that low pollution state occurs.		
\overline{P}	The expected pollution level under $I_l (\equiv \theta P_h + (1 - \theta) P_l)$.		
S	Social damage cost (external cost) per unit of pollution level.		
r.	The probability of the firm making a high investment to honestly declare a high pollution		
1 h	state given state <i>H</i> occurs.		
Y_l	The probability of the firm making a low investment to honestly declare a high pollution		
	state given state <i>H</i> occurs.		
t	Normal (pollution) tax rate.		
ť	Punitive (pollution) tax rate.		
A	I he cost of complete audit.		
<u>q</u>	Audit quality.		
C_f	Net expected environmental costs to be considered by the firm.		
C_r	Net expected external costs to be considered by the regulator.		
α_h	The addit probability of sending an independent additor to verify the firm's report of low		
	pollution state under high investment.		
	The audit probability of sending an independent auditor to verify the firm's report of low		
α_l	pollution state under low investment		
	Position of the ander to a meeting.		



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Variable	Definition	Variable	Definition
A_l	$= \left(\frac{\theta}{1-\theta}\right) q d(t' P_h - t P_l)_1$	ΔI_4	$\equiv t \left(\overline{P} - dP_l \right)$
A_2	$= \left(\frac{\theta}{1-\theta}\right) q(t'P_h - tP_l)$	ΔI_5	$= (1 - \theta)\alpha_1 A + (1 - d)s\overline{P}$
α_l	$\equiv \frac{t(P_h - P_l)}{q(t'P_h - tP_l)}$	β_{I}	$\equiv 1 - \frac{(1-d)t\overline{P}}{\Delta I}$
ΔI_l	$\equiv (1-d)t\overline{P}$	β_2	$=1 - \frac{t(\overline{P} - dP_l)}{\Delta I}$
ΔI_2	$\equiv t \left(\overline{P} - dP_l \right)$	β_3	$\equiv 1 - \frac{(1-d)tP_{l}}{\Delta I}$
ΔI_3	$\equiv (1-d)tP_l$		

Table 1. Definitions of variables (continued)

3 RESULTS

Following Guo and Wang (2004), the firm's objective is to minimize the net expected environmental costs $(C_f)^2$. In contrast, the regulator intends to minimize the net expected external costs derived from pollution $(C_r)^3$. Basically, the overall analyses in this section can be classified into two parts. The first one is to address various possible strategy interplays between the regulator's audit policy and the firm's reporting decision, and the second one is to deal with those between the regulator's subsidy policy and the firm's investment decision subject to the results of analyses in part one. With respect to the analyses of part one, the related results under high and low investment will be summarized in Lemmas 1 and 2, respectively.

Lemma 1.

Given
$$q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$$
, if $A \le \left(\frac{\theta}{1 - \theta}\right) q d(t'P_h - tP_l) \equiv A_l$, then $\alpha_h^* = \frac{t(P_h - P_l)}{q(t'P_h - tP_l)}$

and $\Upsilon_h^* = 1$; otherwise, $\alpha_h^* = 0$ and $\Upsilon_h^* = 0$.

Proof. See Appendix.

It is shown in Lemma 1 that, under high investment and in response to the regulator's audit policy, the firm's optimal reporting strategy is one of either honestly declaring high pollution state or dishonestly declaring a low pollution state, given the realized pollution state is high. Responding to the firm's possible strategies, the regulator's optimal audit policy will be dependent on audit cost. If audit cost (A) is not larger than A_1 , the regulator will adopt a mixed strategy of

 $^{^{3}}$ Net expected external costs = expected social damage cost - expected pollution tax revenue + investment subsidy expenditure + expected audit cost.





 $^{^{2}}$ Net expected environmental costs = investment in abatement of pollution - investment subsidy revenue + expected pollution tax.

random audit to induce the firm to honestly declare the pollution state. On the contrary, if audit cost is larger than A_i , the regulator won' t undertake any audit action. Specifically, A_i is contingent on the probability of high pollution, audit quality, normal tax rate, punitive tax rate, and high/low pollution level under high environmental investment. Furthermore, if the firm has made a low investment in abatement of pollution, we also can obtain a similar strategy profile. The related results are summarized in Lemma 2.

Lemma 2.

Given
$$q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$$
, if $A \le \left(\frac{\theta}{1 - \theta}\right) q(t'P_h - tP_l) \equiv A_2$, then $\alpha_l^* = \frac{t(P_h - P_l)}{q(t'P_h - tP_l)}$ and

 $\gamma_l^* = 1$; otherwise, $\alpha_l^* = 0$ and $\gamma_l^* = 0$.

Proof. See Appendix.

In Lemma 2, it can be found the firm's optimal reporting strategy remains to be a strategy of either honest declaration or dishonest declaration, given that the realized pollution state is high. Moreover, the regulator's optimal audit policy will still depend on the condition of audit cost. The regulator won't use a random audit policy unless the audit cost is less than or equal to A_2 , which is larger than A_1 . Meanwhile, A_2 is contingent on the probability of high pollution, audit quality, normal tax rate, punitive tax rate, and high/low pollution level under low environmental investment. While the threshold for using a random audit under low investment is different from that under high investment, the probabilities of random audit under both low and high investments are indifferent, i.e. $\alpha_l^* = \alpha_h^* = \frac{t(P_h - P_l)}{q(t'P_h - tP_l)} \equiv \alpha_l$. To simplify the denotation in the following analyses, A_1 and A_2 are

used to represent the expressions $\left(\frac{\theta}{1-\theta}\right)qd(t'P_h - tP_l)$ and $\left(\frac{\theta}{1-\theta}\right)q(t'P_h - tP_l)$,

respectively. Also, since $q < \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$ will result in $\gamma_h^* = \gamma_l^* = 0$ (no matter how

much the audit cost is) and make a self-reporting regime useless, $q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$ is

an implied assumption in this paper.

After understanding possible interplays between the firm's reporting decision and the regulator's audit policy, we get a step further to considering the possible strategic interplays between the firm's investment decision and the regulator's subsidy policy. In the following Lemmas 3, 4, and 5, according to the condition of audit cost, the regulator's optimal subsidy policy will be presented at the right moment to induce a high investment in abatement of pollution.

Lemma 3.

Under $A \le A_l$, if $\Delta I \le \Delta I_l$, then $\beta = 0$ is enough to induce $I = I_h$; but if $\Delta I > \Delta I_l$, then $\beta \ge \beta_l$ is necessary to induce $I = I_h$. Meanwhile, $\Delta I \equiv I_h - I_l$, $I_l \equiv (1-d) t \overline{P}$, $\overline{P} \equiv \theta P_h + (1-\theta) P_l$, and $\beta_l \equiv 1 - \frac{(1-d)t\overline{P}}{\Delta I}$.





Proof. See Appendix.

As the audit cost is relatively low, i.e. $A \le A_I$, Lemma 3 shows that if the increased investment (ΔI) doesn't exceed the savings in expected pollution tax (ΔI_I), the firm will choose to make a high investment in abatement of pollution even in the absence of subsidy. However, if the increased investment is larger than the savings in expected pollution tax, the firm will tend to make a low investment in abatement of pollution unless the potential loss can be compensated by the investment subsidy.

From the results of Lemmas 1, 2, and 3, we can derive the possible strategy equilibrium in Proposition 1.

Proposition 1.

Under $A \le A_l$, (1) if $\Delta I \le (1-d) t\overline{P}$, then $\beta^* = 0$, $I^* = I_h$, $\alpha_h = \alpha_l$, and $Y_h^* = 1$; (2) if $(1-d)t\overline{P} < \Delta I < (1-d)s\overline{P}$, then $\beta^* = \beta_l$, $I^* = I_h$, $\alpha_h^* = \alpha_l$, $Y_h^* = 1$; (3) if $\Delta I \ge (1-d)s\overline{P}$, then $\beta^* = 0$, $I^* = I_l$, $\alpha_l^* = \alpha_l$, and $Y_l^* = 1$; where $\Delta I \equiv I - I_l$, $\overline{P} \equiv \theta P_h + (1-\theta)P_l$, $\alpha_l \equiv \frac{t(P_h - P_l)}{q(t'P_h - tP_l)}$, and $\beta_l \equiv 1 - \frac{(1-d)t\overline{P}}{\Delta I}$.

Proof. See Appendix.

From the results of Proposition 1, as audit cost is relatively insignificant, the regulator will offer the firm an investment subsidy only when the increased investment is larger than the latter's savings in expected pollution tax, but less than the savings in expected social damage from pollution. Otherwise, the investment subsidy will become either unnecessary (if $\Delta I \leq (1-d)t\overline{P}$), or uneconomical (if $\Delta I \geq (1-d)s\overline{P}$). Since audit cost is relatively lower, the regulator will undertake a random audit if the firm declares a low pollution state no matter whether the firm has made a high investment or not. Responding to the regulator's audit policy, the firm will choose to honestly declare its pollution state irrespective of making a high or low investment.

Next, in Lemma 4, provided the audit cost is relatively moderate (i.e. $A_1 < A \le A_2$), we can acquire a result similar to Lemma 3.

Lemma 4.

Under $A_1 < A \le A_2$, if $\Delta I \le \Delta I_2$, then $\beta = 0$ is enough to induce $I = I_h$; but if ΔI > ΔI_2 , then $\beta \ge \beta_2$ is necessary to induce $I = I_h$. Meanwhile, $\Delta I \equiv I_h - I_l$, $\Delta I_2 \equiv t(\overline{P} - dP_l)$, $\overline{P} \equiv \theta P_h + (1 - \theta)P_l$, and $\beta_2 \equiv 1 - \frac{t(\overline{P} - dP_l)}{\Delta I}$.

Proof. See Appendix.

As shown in Lemma 4, if the increased investment (ΔI) is not more than the savings in expected pollution tax (ΔI_2), the firm will be inclined to make a high investment in abatement of pollution even without subsidy; but if the increased investment exceeds the savings in expected pollution tax, the firm will choose to make a low investment in abatement of pollution unless the potential loss can be





compensated by the investment subsidy. Nevertheless, the threshold of subsidy in Lemma 4 is higher than that in Lemma 3 since $\Delta I_2 > \Delta I_1$, but the rate of subsidy in the former is lower than that in the latter since $\beta_2 < \beta_1$.

From the results of Lemmas 1, 2, and 4, we can obtain another possible strategy equilibrium, specifically under $A_1 < A \le A_2$, in Proposition 2.

Proposition 2.

Under $A_l < A \le A_2$, (1) if $\Delta I \le t(\overline{P} - dP_l)$, then $\beta^* = 0$, $I^* = I_h$, $\alpha_h^* = 0$, and $\Upsilon_h^* = 0$; (2) if $t(\overline{P} - dP_l) < \Delta I < (1 - \theta)\alpha_l A + (1 - d)s\overline{P}$, then $\beta^* = \beta_2$, $I^* = I_h$, $\alpha_h^* = 0$, and $\Upsilon_h^* = 0$; (3) if $\Delta I \ge (1 - \theta)\alpha_l A + (1 - d)s\overline{P}$, then $\beta^* = 0$, $I^* = I_l$, $\alpha_l^* = \alpha_l$, and $\Upsilon_l^* = 1$; where $\Delta I = I_h - I_l$, $\overline{P} = \theta P_h + (1 - \theta) P_l$, $\alpha_l = \frac{t(P_h - P_l)}{q(t'P_h - tP_l)}$, and $\beta_2 = 1 - \frac{t(\overline{P} - dP_l)}{\Delta I}$.

Proof. See Appendix.

In Proposition 2, as audit cost is relatively moderate (i.e. $A_I < A \le A_2$), the regulator will tend to offer the investment subsidy only when the increased investment is larger than the firm's savings in expected pollution tax, but less than the regulator's savings in both expected audit cost and expected social damage from pollution. Otherwise, the investment subsidy will become either unnecessary (if $\Delta I \le t(\overline{P}-dP_1)$) or uneconomical (if $\Delta I \ge (1 - \theta)\alpha_I A + (1-d)s\overline{P}$). Under the subsidy policy, the firm will make a high investment in abatement of pollution provided the increased investment is less than the sum of the regulator's savings in expected audit cost is moderate, the regulator will take a random audit only when the firm has made a low investment. Responding to the regulator's possible audit policy, the firm will choose to honestly declare a high pollution state, given that a high pollution state is realized only if the latter has made a low investment. In other words, having made a high investment, the firm will under-declare the pollution state given a realized state of high pollution.

Finally, as audit cost becomes considerably significant (i.e. $A > A_2$), the regulator's optimal subsidy policy to induce the firm to make a high investment in abatement of pollution is presented in Lemma 5.

Lemma 5.

Under $A > A_2$, if $\Delta I \le \Delta I_3$, then $\beta = 0$ is enough to induce $I = I_h$; but if $\Delta I > \Delta I_3$, then $\beta \ge \beta_3$ is necessary to induce $I = I_h$. Meanwhile, $\Delta I = I_h - I_l$, $\Delta I_3 = (1 - d)tP_l$, and $\beta_3 = 1 - \frac{(1-d)tP_l}{\Delta I}$.

Proof. See Appendix.

Comparing the result of Lemma 5 with those of Lemmas 3 and 4, it can be found that the threshold of subsidy in Lemma 5 is lower than those in Lemmas 3 and 4, but the rate of subsidy in Lemma 5 is higher than those in Lemmas 3 and 4. In fact, since $\Delta I_2 > \Delta I_1 > \Delta I_3$, and $\beta_2 < \beta_1 < \beta_3$, ceteris paribus, there exist the highest





threshold of subsidy and the lowest rate of subsidy as $A_1 < A \le A_2$, but it can lead to the lowest threshold of subsidy and the highest rate of subsidy as $A > A_2$.⁴

Hence, from the results of Lemmas 1, 2 and 5, we can derive the possible strategy equilibrium under $A > A_2$, as shown in Proposition 3.

Proposition 3.

Under $A > A_2$, (1) if $\Delta I \le (1-d)tP_l$, then $\beta^* = 0$, $\mathring{I} = I_h$, $\alpha_h^* = 0$, and $\Upsilon_h^* = 0$; (2) if $(1-d)tP_l < \Delta I < (1-d)s\overline{P}$, then $\beta^* = \beta_3$, $\mathring{I} = I_h$, $\alpha_h^* = 0$, and $\Upsilon_h^* = 0$; (3) if $\Delta I \ge (1-d)s\overline{P}$, then $\beta^* = 0$, $\mathring{I} = I_l$, $\alpha_l^* = 0$, and $\Upsilon_l^* = 0$; where $\Delta I \equiv I_h - I_l$, $\overline{P} \equiv \theta P_h + (1-\theta)P_l$, and $\beta_3 \equiv 1 - \frac{(1-d)tP_l}{\Delta I}$.

Proof. See Appendix.

As audit cost becomes considerably significant, the regulator will offer the investment subsidy only if the increased investment is larger than the firm's savings in expected pollution tax, but less than the savings in expected social damage from pollution. Otherwise, the investment subsidy will be neither necessary (if $\Delta I \le (1 - d)tP_l$) nor economical (if $\Delta I \ge (1 - d)s\overline{P}$). Under the subsidy policy, the firm will make a high investment in abatement of pollution provided the increased investment is less than the savings in expected social damage from pollution. Additionally, since audit cost is relatively significant, it is uneconomical for the regulator to undertake any audit action no matter whether the firm has made a high investment or not. Thus, the firm will tend to dishonestly declare a low pollution state under a high pollution state no matter what investment the firm has made.

From the results of Propositions 1 to 3, there are different policy combinations within various possible ranges of audit cost. It is obvious that the strategy equilibrium will change with audit cost. The related results are summarized in Table 2, where it can be found that as audit cost becomes considerably significant (i.e. $A > A_2$), the regulator will be inclined to use a subsidy policy and to totally abandon audit policy. In that case, not only does the threshold of subsidy become lower (i.e. $\Delta I_1 < \Delta I_2$) than that as the audit cost is insignificant (i.e. $A \le A_1$), but also the subsidy rate will be relatively higher (i.e. $\beta_3 > \beta_1$). That implies, as environmental audit is difficult and costly, that the subsidy on the investment in abatement of pollution can be much more effective and justifiable. Additionally, if audit cost is relatively moderate (i.e. $A_1 < A \le A_2$), the regulator will tend to take an effective (random) audit policy for low-investment firms, but will give up audit measure for high-investment firms.

⁴ ΔI_3 denotes the savings in expected pollution tax as $A > A_2$ and the firm makes a high (rather than low) investment.





The Range of Audit Cost	$A \leq A_I$	$A_l < A \le A_2$	$A > A_2$		
Audit Policy α_h^*	$ = \alpha_l^* = \frac{t(P_h - P_l)}{q(t'P_h - tP_l)} $	$\alpha_{h}^{*} = 0, \ \alpha_{l}^{*} = \frac{t(P_{h} - P_{l})}{q(t'P_{h} - tP_{l})}$	$\alpha_h^* = \alpha_l^* = 0$		
Self-Reporting Decision	$\Upsilon_h^* = \Upsilon_l^* = 1$	$\gamma_h^* = 0, \ \gamma_l^* = 1$	$\gamma_h^* = \gamma_l^* = 0$		
Possible Subsidy Policy and Investment Decision	$(i) \begin{cases} \beta^* = 0 \\ I^* = I_h \\ \text{if } \Delta I \le \Delta I_2 \\ (ii) \begin{cases} \beta^* = \beta_1 \\ I^* = I_h \\ \text{if } \Delta I_2 < \Delta I < \Delta I_3 \end{cases}$ $(ii) \begin{cases} \beta^* = 0 \\ I^* = I_l \\ \text{if } \Delta I \ge \Delta I_3 \end{cases}$	(i) $\begin{cases} \beta^* = 0 \\ I^* = I_h \\ \text{if } \Delta I \le \Delta I_4 \\ (ii) \begin{cases} \beta^* = \beta_2 \\ I^* = I_h \\ \text{if } \Delta I_4 < \Delta I < \Delta I_5 \end{cases}$ (ii) $\begin{cases} \beta^* = 0 \\ I^* = I_l \\ \text{if } \Delta I \ge \Delta I_5 \end{cases}$	$(i) \begin{cases} \beta^* = 0 \\ I^* = I_h \\ \text{if } \Delta I \le \Delta I_1 \\ (ii) \begin{cases} \beta^* = \beta_3 \\ I^* = I_h \\ \text{if } \Delta I_1 < \Delta I < \Delta I_3 \\ (ii) \begin{cases} \beta^* = 0 \\ I^* = I_l \\ \text{if } \Delta I \ge \Delta I_3 \end{cases}$		
${}^{*}A_{1} \equiv \left(\frac{\theta}{1-\theta}\right) q d(t'P_{h}-tP_{l}), A_{2} \equiv \left(\frac{\theta}{1-\theta}\right) q(t'P_{h}-tP_{l}), \Delta I_{1} \equiv (1-d)tP_{l}, \Delta I_{2} \equiv (1-d)t\overline{P}, \Delta I_{3} \equiv (1-d)s\overline{P}, \Delta I_{3} \equiv (1-d)s\overline{P}$					
$\Delta I_4 \equiv t \left(\overline{P} - dP_1\right), \Delta I_5 \equiv (1 - \theta)\alpha_1 A + (1 - d)s \overline{P} \text{ , and } \Delta I_1 < \Delta I_2 < \Delta I_3 (\Delta I_4) < \Delta I_5. \text{ In addition, } \beta_3 > \beta_1 \text{ given}$					
the same ΔI .					

Tabl	e 2.	Policy	summary
		~	~

4. CONCLUSIONS

To induce a polluting firm to make a necessary investment in environmental protection, the regulator needs to employ some policy measures as economic incentives. Among others, the subsidy on the investment in abatement of pollution and the tax imposed on the pollution, subject to possible audit, are often regarded as two important incentives contributing toward alleviating the costly externalities of pollutions generated by optimizing economic firms. Since there is some evidence in the literature to justify a self-reporting regime, this paper simultaneously addresses the issues of subsidy, audit and self-reporting in environmental policy. Following Guo and Wang (2004), this paper uses a principal-agent model to examine the interplays among these regulatory measures.

Assuming the auditor is absolutely independent and has basic audit capability, i.e. audit quality is over some threshold level, we find that in response to the regulator's audit policy the firm's optimal reporting strategy under high (or low) investment is either honestly declaring a high pollution state or dishonestly declaring a low pollution state given that the realized state of pollution is high. In contrast, responding to the firm's possible strategy, the regulator's optimal audit policy will be either a mixed one with some audit probability or a pure one with no audit, depending on the condition of audit cost. While the threshold for using





random audit under high investment is stricter than that under low investment, the probabilities of random audit under either high or low investments are indifferent and mainly contingent on audit quality, tax rates and pollution levels.

A little different from the result of Guo and Wang (2004), under a self-reporting regime, there seems to be no strong policy substitutability between subsidy and audit measures. As shown in this paper, when audit cost is insignificant, the regulator can still resort to subsidy measures in addition to an effective audit policy, while such a subsidy measure will never be considered under no self-reporting in Guo and Wang. Nevertheless, as audit cost becomes considerably significant, the regulator will be inclined to adequately use subsidy policy and totally abandon audit policy. In that case, not only does the threshold of subsidy become lower than that as audit cost is insignificant, but also the subsidy rate is relatively higher. That implies, as environmental audit is difficult and costly, the subsidy on the investment in abatement of pollution can be much more effective and justifiable.

If audit cost is relatively moderate, the regulator will take an effective audit action only if the firm has made a low investment; and responding to the regulator's audit policy, the firm will honestly declare its pollution state. In contrast, under high investment, the firm will under-declare the pollution state, given a high pollution state occurs, due to no audit threat. When audit cost is insignificant, in consideration of the effective audit from the regulator, the firm will honestly declare a high pollution state no matter if it is under high or low investment.

Essentially, whether the regulator needs to employ a subsidy policy or not depends not only on if the subsidy is necessary to induce high investment but also on if subsidy policy is economically better than the no subsidy policy. Additionally, the normal tax rate on pollution plays a prominent role in both subsidy and audit polices. Ceteris paribus, the lower is the normal tax rate of pollution, the higher the subsidy rate will be, but the lower will be the probability of a random audit. However, as the normal tax rate of pollution increases, it will enhance the possibility of the firm voluntarily undertaking a high investment, even in the scarcity of a subsidy.

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Appendix

Proof of Lemma 1.

Given that the firm has made a high investment in abatement of pollution, if a realized state of pollution is high, the firm can choose to declare a high pollution state or a low pollution state, and then acquire the related costs $C_f(Y_h = 1 | I_h, P_h)$ or $C_f(Y_h = 0 | I_h, P_h)$, where C_f denotes the firm's net expected environmental costs. Thus, the firm will choose $Y_h = 1$ only if: $C_f(Y_h = 1 | I_h, P_h) \le C_f(Y_h = 0 | I_h, P_h)$ $\Leftrightarrow I_h - \beta \Delta I + tdP_h \le I_h - \beta \Delta I + \alpha_h [q t'dP_h + (1 - q) tdP_l] + (1 - \alpha_h) tdP_l$ $\Leftrightarrow \alpha_h [qt'dP_h + (1 - q) tdP_l - tdP_l] \ge td (P_h - P_l)$

 $\Leftrightarrow \alpha_h \geq \frac{t(P_h - P_l)}{q(t'P_h - tP_l)} \equiv \alpha_1$

Also, to ensure $\alpha_1 \le 1$, we need $q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$ to hold; otherwise, there will

not be enough incentive for the firm to choose $\gamma_h = 1$.

On the other hand, given $q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$ and the firm's high investment, the

regulator can choose either to induce the firm to take $\Upsilon_h = 1$ by setting a audit probability up to α_1 or to let the firm adopt $\Upsilon_h = 0$ by setting some audit probability, e.g. α_1 , less than α_1 and then obtain the related costs $C_r (\alpha_h = \alpha_1 | I_h)$ or $C_r (\alpha_h = \alpha_1 | I_h)$, where C_r denotes the regulator's net expected external costs.

Hence, the regulator's net expected external costs will be:

either $C_r(\alpha_h = \alpha_1 | I_h) = \beta \Delta I + (1 - \theta) \alpha_1 A - \theta t dP_h - (1 - \theta) t dP_l + sd [\theta P_h + (1 - \theta) P_l]$ or $C_r(\alpha_h = \alpha_1 | I_h) = \beta \Delta I + \alpha_1 A - \theta \alpha_1 qt' dP_h - (1 - \theta \alpha_1 q) t dP_l + sd [\theta P_h + (1 - \theta) P_l]$, depending upon whether it chooses $\alpha_h = \alpha_1$ or $\alpha_h = \alpha_1$.

Furthermore, since $\partial C_r(\alpha_h = \alpha_1 | I_h) / \partial \alpha_1 = A - \theta q d (t \mathcal{P}_h - t \mathcal{P}_l)$, the regulator will set $\alpha_1 = \alpha_1 - \varepsilon$, where $\varepsilon > 0$ and $\varepsilon \to 0$, if $A \le \theta q d (t \mathcal{P}_h - t \mathcal{P}_l)$; otherwise, it will take $\alpha_1 = 0$. Therefore, given $q \ge \frac{t(\mathcal{P}_h - \mathcal{P}_l)}{(t'\mathcal{P}_h - t\mathcal{P}_l)}$, if $A \le \theta q d (t \mathcal{P}_h - t \mathcal{P}_l)$;

 tP_l), then the regulator's optimal audit policy will be $\alpha_h^* = \alpha_1$ and the firm's optimal reporting decision will be $\gamma_h^* = 1$ as long as $C_r (\alpha_h = \alpha_1 | I_h) \le (\alpha_h = \alpha_1 - \varepsilon | I_h)$, which necessarily holds since:

 $C_r \left(\alpha_h = \alpha_1 \mid I_h \right) \le C_r \left(\alpha_h = \alpha_1 - \varepsilon \mid I_h \right)$

 $\Leftrightarrow (1-\theta) \ \alpha_1 A - \theta t dP_h - (1-\theta) \ t dP_l \le (\alpha_1 - \varepsilon) \ A - \theta(\alpha_1 - \varepsilon) \ qt' dP_h - [1-\theta(\alpha_1 - \varepsilon) q] \ t dP_l$

 $\Leftrightarrow -\theta \alpha_1 A - \theta t d (P_h - P_l) \leq -\varepsilon A - \theta (\alpha_1 - \varepsilon) q t' dP_h + \theta (\alpha_1 - \varepsilon) q t dP_l$ $\Leftrightarrow \theta \alpha_1 A + \theta t d (P_h - P_l) - \theta \alpha_1 q d (t P_h - tP_l) \geq \varepsilon [A - \theta q d (t P_h - tP_l)]$ $\Leftrightarrow \theta \alpha_1 A \geq \varepsilon [A - \theta q d (t P_h - tP_l)] \rightarrow 0$

On the other hand, given $q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$, if $A > \theta q d (t P_h - tP_l)$, then $\alpha_h^* = \alpha_1$

and $\Upsilon_h^* = 1$ as long as $C_r (\alpha_h = \alpha_1 | I_h) \le C_r (\alpha_h = 0 | I_h)$, which holds only if $A \le A_I$ since:





$$C_{r} (\alpha_{h} = \alpha_{1} \mid I_{h}) \leq C_{r} (\alpha_{h} = 0 \mid I_{h})$$

$$\Leftrightarrow (1 - \theta) \alpha_{1}A - \theta t dP_{h} - (1 - \theta) t dP_{l} \leq -t dP_{l}$$

$$\Leftrightarrow \frac{(1 - \theta)At(P_{h} - P_{l})}{q(t'P_{h} - tP_{l})} \leq \theta t d (P_{h} - P_{l})$$

$$\Leftrightarrow A \leq \left(\frac{\theta}{1 - \theta}\right) q d (t P_{h} - tP_{l}) \equiv A_{l}.$$
That is, given $q \geq \frac{t(P_{h} - P_{l})}{(t'P_{h} - tP_{l})}$, if $\theta q d (t P_{h} - tP_{l}) < A \leq A_{l}$, then $\alpha_{h}^{*} = \alpha_{1}$ and

 $\Upsilon_h^* = 1$; but if $A > A_I$, then $\alpha_h^* = 0$ and $\Upsilon_h^* = 0$.

Proof of Lemma 2.

Given that the firm has made a low investment in abatement of pollution, if a high pollution state is realized, the firm can choose to declare a high pollution state or a low pollution state, and then acquire the related costs $C_f(\gamma_l = 1 | I_l, P_h)$ or $C_f(\gamma_l = 0 | I_l, P_h)$, where C_f denotes the firm's net expected environmental costs. Thus, the firm will choose $\gamma_l = 1$ only if:

 $C_{f}(Y_{l} = 1 \mid I_{l}, P_{h}) \leq C_{f}(Y_{l} = 0 \mid I_{l}, P_{h})$ $\Leftrightarrow I_{l} + tP_{h} \leq I_{l} + \alpha_{1} [qtP_{h} + (1 - q) tP_{l}] + (1 - \alpha_{l}) tP_{l}$ $\Leftrightarrow \alpha_{l} [qtP_{h} + (1 - q) tP_{l} - tP_{l}] \geq t (P_{h} - P_{l})$ $\Leftrightarrow \alpha_{l} \geq \frac{t(P_{h} - P_{l})}{q(t'P_{h} - tP_{l})} \equiv \alpha_{1}$

Also, to ensure $\alpha_1 \le 1$, we need $q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$ to hold; otherwise, there will not be enough incentive for the firm to choose $\gamma_l = 1$.

On the other hand, given $q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$ and the firm's low investment, the regulator can choose either to induce the firm to take $\Upsilon_l = 1$ by setting a audit probability up to α_1 or to let the firm adopt $\Upsilon_l = 0$ by setting some audit probability,

e.g. α_1 , less than α_1 , and then obtain the related costs C_r ($\alpha_l = \alpha_1 | I_l$) or C_r ($\alpha_l = \alpha_1 | I_l$), where C_r denotes the regulator's net expected external costs. Hence, the regulator's net expected external costs will be:

either $C_r (\alpha_l = \alpha_1 | I_l) = (1 - \theta) \alpha_1 A - \theta t P_h - (1 - \theta) t P_l + s [\theta P_h + (1 - \theta) P_l]$ or $C_r (\alpha_l = \alpha_1 | I_l) = \alpha_1 A - \theta \alpha_1 q t P_h - (1 - \theta \alpha_1 q) t P_l + s [\theta P_h + (1 - \theta) P_l]$ depending upon whether it chooses $\alpha_h = \alpha_l$ or $\alpha_h = \alpha_1$.

Furthermore, since $\partial C_r (\alpha_l = \alpha_1 | I_l) / \partial \alpha_1 = A - \theta q(t \mathcal{P}_h - t\mathcal{P}_l)$, the regulator will set $\alpha_1 = \alpha_1 - \varepsilon$, where $\varepsilon > 0$ and $\varepsilon \to 0$, if $A \le \theta q(t \mathcal{P}_h - t\mathcal{P}_l)$; otherwise, it will take $\alpha_1 = 0$. Therefore, given $q \ge \frac{t(\mathcal{P}_h - \mathcal{P}_l)}{(t'\mathcal{P}_h - t\mathcal{P}_l)}$, if $A \le \theta q(t \mathcal{P}_h - t\mathcal{P}_l)$, then the regulator's optimal audit policy will be $\alpha_l^* = \alpha_1$ and the firm's optimal reporting decision will be $\gamma_l^* = 1$ as long as $C_r (\alpha_l = \alpha_1 | I_l) \le C_r (\alpha_l = \alpha_1 - \varepsilon | I_l)$, which necessarily holds since:

 $C_r (\alpha_l = \alpha_1 | I_l) \le C_r (\alpha_l = \alpha_1 - \varepsilon | I_l)$ $\Leftrightarrow (1 - \theta) \alpha_1 A - \theta t P_h - (1 - \theta) t P_l \le (\alpha_1 - \varepsilon) A - \theta (\alpha_1 - \varepsilon) q t P_h - [1 - \theta (\alpha_1 - \varepsilon) q]$ $t P_l$





 $\Leftrightarrow -\theta \alpha_1 A - \theta t(P_h - P_l) \le -\varepsilon A - \theta (\alpha_1 - \varepsilon) qt P_h + \theta (\alpha_1 - \varepsilon) qt P_l$ $\Leftrightarrow \theta \alpha_1 A + \theta t(P_h - P_l) - \theta \alpha_1 q (t P_h - tP_l) \ge \varepsilon [A - \theta q(t P_h - tP_l)]$ $\Leftrightarrow \theta \alpha_1 A \ge \varepsilon [A - \theta q(t P_h - tP_l)] \to 0.$

On the other hand, given $q \ge \frac{t(P_h - P_l)}{(t'P_h - tP_l)}$, if $A > \theta q(t P_h - tP_l)$, then $\alpha_l^* = \alpha_1$

and $Y_l^* = 1$ as long as $C_r (\alpha_l = \alpha_1 | I_l) \le C_r (\alpha_l = 0 | I_l)$, which holds only if $A \le A_2$ since:

$$C_{r} (\alpha_{l} = \alpha_{1} | I_{l}) \leq C_{r} (\alpha_{l} = 0 | I_{l})$$

$$\Leftrightarrow (1 - \theta) \alpha_{1}A - \theta tP_{h} - (1 - \theta) tP_{l} \leq -tP_{l}$$

$$\Leftrightarrow \frac{(1 - \theta)At(P_{h} - P_{l})}{q(t'P_{h} - tP_{l})} \leq \theta t(P_{h} - P_{l})$$

$$\Leftrightarrow A \leq \left(\frac{\theta}{1 - \theta}\right)q(t'P_{h} - tP_{l}) \equiv A_{2}$$
That is, given $q \geq \frac{t(P_{h} - P_{l})}{(t'P_{h} - tP_{l})}$, if $\theta q(t'P_{h} - tP_{l}) < A \leq A_{2}$, then $\alpha_{l}^{*} = \alpha_{1}$ and $\gamma_{l}^{*} = \alpha_{1}$

1; but if $A > A_2$, then $\alpha_l^* = 0$ and $\gamma_l^* = 0$.

Proof of Lemma 3.

From Lemmas 1 and 2, if $A \le A_1(< A_2)$, then $\alpha_h^* = \alpha_l^* = \alpha_1$ and $\Upsilon_h^* = \Upsilon_l^* = 1$. Hence, given a subsidy rate of β^* , the firm will make a high investment only if: C_f $(I_h | \beta = \beta^*, \alpha_h = \alpha_1) \le C_f (I_l | \beta = 0, \alpha_l = \alpha_1)$. Since: $C_f (I_h | \beta = \beta^*, \alpha_h = \alpha_1) \le C_f (I_l | \beta = 0, \alpha_l = \alpha_1)$ $\Leftrightarrow I_h - \beta^* \Delta I + td\overline{P} \le I_l + t\overline{P}$ $\Leftrightarrow \beta^* \Delta I \ge \Delta I - (1 - d) t\overline{P}$ $\Leftrightarrow \beta^* \ge 1 - \frac{(1 - d)t\overline{P}}{\Delta I} = \beta_1$,

the regulator needs to set $\beta^* \ge \beta_1$ to induce a high investment if $\Delta I \ge (1 - d) t \overline{P}$, but $\beta^* = 0$ is enough to induce a high investment if $\Delta I \le (1 - d) t \overline{P}$.

Proof of Proposition 1.

From the results of Lemmas 1, 2 and 3, given $A \le A_1$ and $\Delta I \ge (1 - d) t\overline{P}$, the regulator will offer a subsidy rate of β_1 to induce a high investment only if: $C_r (\beta = \beta_1, I = I_h, \alpha_h = \alpha_1, \Upsilon_h = 1) < C_r (\beta = 0, I = I_l, \alpha_l = \alpha_1, \Upsilon_l = 1)$ $\Leftrightarrow \beta_1 \Delta I + (1 - \theta) \alpha_1 A - td\overline{P} + sd\overline{P} < (1 - \theta)\alpha_1 A - t\overline{P} + s\overline{P}$ $\Leftrightarrow \Delta I + sd\overline{P} < s\overline{P}$ $\Leftrightarrow \Delta I < (1 - d) s\overline{P}$ Hence, given $A \le A_1$, if $(1 - d) t\overline{P} < \Delta I < (1 - d) s\overline{P}$, we have $\beta^* = \beta_1$, $\mathring{I} = I_h$, $\alpha_h^* = \alpha_1$, and $\Upsilon_h = 1$; but if $\Delta I \ge (1 - d) s\overline{P}$, then $\beta^* = 0$, $\mathring{I} = I_l$, $\alpha_l^* = \alpha_1$, and $\Upsilon_l^* = 1$.

On the other hand, given $A \le A_1$, if $\Delta I \le (1 - d) t \overline{P}$, the regulator will prefer a high investment under no subsidy since:

 $C_r (\beta = 0, I = I_h, \alpha_h = \alpha_1, Y_h = 1) < C_r (\beta = 0, I = I_l, \alpha_l = \alpha_1, Y_l = 1)$ $\Leftrightarrow (1 - \theta)\alpha_1 A - t\overline{P} + s\overline{P}$





 $\Leftrightarrow (1-d) t\overline{P} < (1-d) s\overline{P} \quad (\because t < s).$ Thus, given $A \le A_1$, if $\Delta I < (1-d) t\overline{P}$, we have $\beta^* = 0$, $I = I_h$, $\alpha_h^* = \alpha_1$, and $\gamma_h^* = 1$.

Proof of Lemma 4.

From Lemmas 1 and 2, if $A_1 \le A \le A_2$, then $\alpha_h^* = 0$, $\alpha_l^* = \alpha_1$, $\gamma_h^* = 0$, and $\gamma_l^* = 1$. Hence, given a subsidy rate of β^* , the firm will make a high investment only if: $C_f(I_h | \beta = \beta^*, \alpha_h = 0) \le C_f(I_l | \beta = 0, \alpha_l = \alpha_1)$. Since: $C_f(I_h | \beta = \beta^*, \alpha_h = 0) \le C_f(I_l | \beta = 0, \alpha_l = \alpha_1)$ $\Leftrightarrow I_h - \beta^* \Delta I + tdP_l \le I_l + t\overline{P}$

 $\Leftrightarrow \beta^* \Delta I \ge \Delta I - t \left(\overline{P} - dP_l \right)$ $\Leftrightarrow \beta^* \ge 1 - \frac{t (\overline{P} - dP_l)}{\Delta I} \equiv \beta_2,$

the regulator needs to set $\beta^* \ge \beta_2$ to induce a high investment if $\Delta I > t(\overline{P} - dP_l)$, but

 $\beta^* = 0$ is enough to induce a high investment if $\Delta I \le t (\overline{P} - dP_l)$.

Proof of Proposition 2.

From the results of Lemmas 1, 2 and 4, given $A_1 < A \le A_2$ and $\Delta I > t(\overline{P} - dP_l)$,

the regulator will offer a subsidy rate of β_2 to induce a high investment only if:

 $C_r (\beta = \beta_2, I = I_h, \alpha_h = 0, Y_h = 0) < C_r (\beta = 0, I = I_l, \alpha_l = \alpha_1, Y_l = 1)$ $\Leftrightarrow \beta_2 \Delta I - tdP_l + sd\overline{P} < (1 - \theta)\alpha_1 A - t\overline{P} + s\overline{P}$ $\Leftrightarrow \Delta I + sd\overline{P} < (1 - \theta)\alpha_1 A + s\overline{P}$ $\Leftrightarrow \Delta I < (1 - \theta)\alpha_1 A + (1 - d)s\overline{P}$

Hence, given $A_1 < A \le A_2$, if $t(\overline{P} - dP_l) < \Delta I < (1 - \theta)\alpha_1 A + (1 - d) s\overline{P}$, then we have $\beta^* = \beta_2$, $\tilde{I} = I_h$, $\alpha_h^* = 0$, and $\gamma_h^* = 0$; but if $\Delta I \ge (1 - \theta)\alpha_1 A + (1 - d) s\overline{P}$, then $\beta^* = 0$, $\tilde{I} = I_l$, $\alpha_l^* = \alpha_1$, $\gamma_l^* = 1$.

On the other hand, given $A_1 < A \le A_2$, if $\Delta I \le t (\overline{P} - dP_l)$, the regulator will

prefer a high investment under no subsidy since:

 $C_r (\beta = 0, I = I_h, \alpha_h = 0, Y_h = 0) < C_r (\beta = 0, I = I_l, \alpha_l = \alpha_1, Y_l = 1)$ $\Leftrightarrow -tdP_l + sd\overline{P} < (1 - \theta)\alpha_1 A - t\overline{P} + s\overline{P}$ $\Leftrightarrow \frac{(1 - \theta)t(P_h - P_l)A}{q(t'P_h - tP_l)} > t\overline{P} - s\overline{P} - tdP_l + sd\overline{P}$ $\Leftrightarrow \theta dt (P_h - P_l) > t\overline{P} - s\overline{P} - tdP_l + sd\overline{P} \quad (\because A > A_1)$ $\Leftrightarrow (1 - d) s\overline{P} > t\overline{P} - \theta dtP_h - (1 - \theta) tdP_l$ $\Leftrightarrow (1 - d) s\overline{P} > t\overline{P} - dt \left(\theta P_h + (1 - \theta) P_l\right)$ $\Leftrightarrow (1 - d) s\overline{P} > (1 - d) t\overline{P} \quad (\because s > t)$



Thus, given $A_1 < A \le A_2$, if $\Delta I \le t \left(\overline{P} - dP_l\right)$, then we have $\beta^* = 0$, $I^* = I_h$, $\alpha_h^* = 0$, $\gamma_h^* = 0$.

Proof of Lemma 5.

From Lemmas 1 and 2, if $A > A_2$, then $\alpha_h^* = \alpha_l^* = 0$ and $\Upsilon_h^* = \Upsilon_l^* = 0$. Hence, given a subsidy rate of β^* , the firm will make a high investment only if: $C_f(I_h | \beta = \beta^*, \alpha_h = 0) \le C_f(I_l | \beta = 0, \alpha_l = 0)$.

Since:

 $C_{f}(I_{h} | \beta = \beta^{*}, \alpha_{h} = 0) \leq C_{f}(I_{l} | \beta = 0, \alpha_{l} = 0)$ $\Leftrightarrow I_{h} - \beta^{*} \Delta I + tdP_{l} \leq I_{l} + tP_{l}$ $\Leftrightarrow \beta^{*} \Delta I \geq \Delta I - (1 - d) tP_{l}$ $\Leftrightarrow \beta^{*} \geq 1 - \frac{(1 - d)tP_{l}}{\Delta I} \equiv \beta_{3}$

the regulator needs to set $\beta^* \ge \beta_3$ to induce a high investment if $\Delta I > (1 - d) tP_l$, but $\beta^* = 0$ is enough to induce a high investment if $\Delta I \le (1 - d) tP_l$.

Proof of Proposition 3.

From the results of Lemmas 1, 2 and 5, given $A > A_2$, then $\Delta I > (1 - d) tP_1$, the regulator will offer a subsidy rate of β_3 to induce a high investment only if:

 $C_r (\beta = \beta_3, I = I_h, \alpha_h = 0, Y_h = 0) < C_r (\beta = 0, I = I_l, \alpha_l = \alpha_1, Y_l = 0)$ $\Leftrightarrow \beta_3 \Delta I - t dP_l + s d\overline{P} < -tP_l + s\overline{P}$ $\Leftrightarrow \Delta I < (1 - d) s\overline{P}$

Hence, given $A > A_2$, if $(1 - d) tP_l < \Delta I < (1 - d) s\overline{P}$, then we have $\beta^* = \beta_3$, $\overline{I}^* = I_h$, $\alpha_h^* = 0$ and $\gamma_h^* = 0$; but if $\Delta I \ge (1 - d) s\overline{P}$, then $\beta^* = 0$, $\overline{I}^* = I_l$, $\alpha_l^* = 0$ and $\gamma_l^* = 0$.

On the other hand, given $A > A_2$, if $\Delta I \le (1 - d) tP_l$, the regulator will prefer a high investment under no subsidy since:

 $C_r (\beta = 0, I = I_h, \alpha_h = 0, \Upsilon_h = 0) < C_r (\beta = 0, I = I_l, \alpha_l = 0, \Upsilon_l = 0)$ $\Leftrightarrow -tdP_l + sd\overline{P} < -tP_l + s\overline{P}$ $\Leftrightarrow (1 - d) tP_l < (1 - d) s\overline{P} \quad (\because t < s \text{ and } P_l < \overline{P})$ Thus, given $A > A_2$, if $\Delta I \le (1 - d) tP_l$, then we have $\beta^* = 0$, $I^* = I_h$, $\alpha_h^* = 0$ and $\Upsilon_h^* = 0$.

